# Ahsanullah University of Science and Technology Department of Electrical and Electronic Engineering 

LABORATORY MANUAL.<br>FOR<br>ELECTRICAL AND ELECTRONIC SESSIONAL COURSES

Student Name:
Student ID:

Course no: EEE-2188<br>Course Title : Electrical Machines

For the students of<br>Department of Mechanical and Production Engineering<br>$2^{\text {nd }}$ Year, $1^{\text {th }}$ Semester

Experiment no: $\mathbf{1}$
Experiment name: Study of a Single-Phase Transformer.

## Introduction:

A transformer is a static device by means of which electric power in one circuit is transferred into electric power in another circuit of the same frequency. It can raise or lower voltage in the circuit with a corresponding decrease or increase in current. So the volt-ampere rating of two arcuits remains same. The simple structure of a $1-\phi$ transformer is shown below:


Fig: Simple structure of a 1- $\phi$ transformier
As the volt-ampere rating of two sides are same so

$$
\begin{align*}
V_{1}^{*} I_{1} & =V_{2} * I_{2} \\
\text { i.e. } V_{V} / V_{2} & =I_{2} / I_{1} \tag{1}
\end{align*}
$$

Again the induced voltage in the transformer is directly proportional to the no of turns surrounding the transformer windings. So

$$
\begin{align*}
& V_{1} \times N_{1} \text { and } V_{2} \times N_{2} \\
& \text { i.e. } V_{1} / V_{2}=N_{1} / N_{2} \cdots \tag{2}
\end{align*}
$$

Combining these two equations, (1) and (2) we get

$$
V_{1} / V_{2}=I_{2} / I_{1}=N_{1} / N_{2}
$$

Where $\mathrm{N}_{1} / \mathrm{N}_{2}$ is called the transformation ratio or simply turns ratio of a transformer


## Equipments:

1. Universal Power Supply Module
2. 1PH Transformer
3. AC Ammeter Module $0-1 \mathrm{~A}$
4. AC Voltmeter Module $0-250 \mathrm{~V}$
5. Resistive Load
6. 1PH Wattmeter Module


## Ratio Test:

For a transformer, we know, the transformation ratio is given by

$$
\frac{V_{1}}{V_{2}}=\frac{I_{2}}{I_{1}}=\frac{N_{1}}{N_{2}}
$$

We shall determine the transformation ratio by measuring the voltages and currents both in the primary and secondary side.


1. Make sure all the switches (I1, I2, I3, I4, I5, I6) on the Power Supply are turned OFF (downwards).
2. Make sure all the variable knobs (K1, K3, K4) are at the min, counter clock wise (CCW) position.
3. Make sure all the switches $(1,2,4)$ of the Resistive Load Module are OFF (downwards)
4. Make connections according to the above diagram.
5. Verify the connection by your Lab Teacher
6. Turn ON Switch I1 (upwards).
7. Turn Key K2 Clock Wise Once, the Indicator Lamp L1 becomes Green.
8. Make sure the 3 PH supply Voltmeter V1 reading 400 V .
9. Turn Knob K3 at min (CCW)
10. Turn ON switch I3 (upwards).
11. Slowly Increase 1PH AC Voltage to 110 V , Turn Knob K3 CW, Voltmeter V2 reading
110 V
12. Increase the Resistive Load by turning $O N$ the switches $(1,2,4)$ of the Resistive Load Module.
13. Increase Load until the current becomes 0.5 A , so that power $>=100 \mathrm{~W}$
14. Note the voltages and currents both in the primary and secondary from the AC

## Transformer on No-load/Open Circuit Test:



1. Make sure all the switches (I1, I2, I3, I4, I5, I6) on the Power Supply are turned OFF (downwards).
2. Make sure all the variable knobs (K1, K3, K4) are at the min, counter dock wise (CCW) position.
3. Make connections according to the above diagram.
4. Verify the connection by your Lab Teacher
5. Turn ON Switch I1 (upwards).
6. Turn Key K2 Clock Wise Once, the Indicator Lamp L1 becomes Green.
7. Make sure the 3PH supply Voltmeter V1 reading 400 V .
8. Turn Knob K3 at min (CCW)
9. Turn ON switch I3 (upwards).
10. Slowly Increase 1 PH AC Voltage to 220 V , Turn Knob K3 CW, Voltmeter V2 reading 220V
11. Note the voltages and currents in the primary from the AC Voltmeter \& Ammeter Module

Short Circuit Test: This test determines copper loss in the transformer. Finding this loss the regulation of the transformer can be determined. The circuit arrangement of this test is shown below:


From the wattmeter, voltmeter, ammeter readings, we get

$$
\begin{aligned}
& W_{c U}=W_{S C}=R_{01} * I_{S C}{ }^{2} \quad \text { i.e. } R_{01}=W_{S C} / I_{s c}{ }^{2} \\
& X_{01}=V\left(\left(V / I_{S C}\right)^{2}-R_{01}{ }^{2}\right)
\end{aligned}
$$

## Procedure:

1. Make sure all the switches (I1, I2, I3, I4, I5, I6) on the Power Supply are turned OFF (downwards).
2. Make sure all the variable knobs $(K 3, K 4)$ are at the min, counter clock wise (CCW) position.
3. Make connections according to the above diagram.
4. Verify the connection by your Lab Teacher
5. Turn ON Switch I1 (upwards).
6. Turn Key K2 Clock Wise Once, the Indicator Lamp L1 becomes Green.
7. Turn Knob K3 at min (CCW)
8. Turn ON switch I3 (upwards).
9. Carefully increase the voltage till the rated current $(300 \mathrm{VA}+220 \mathrm{~V}=1.4 \mathrm{~A})$
flows through the HT , Turn Knob K3 CW
10. Note the readings on AC Voltmeter, Ammeter and Wattmeter Module

## *** For each case write down the data on data sheet.

## Report:

1. What effects are produced in a transformer by change in voltage?
2. Does the transformer draw any current when its secondary is open? If yes, then why?

## Group No: Roll no:

## Data Sheet

## Ratio test:

$\mathrm{V}_{1}=\quad \mathrm{V}_{2}=\quad \mathrm{I}_{1}=\quad \mathrm{I}_{2}=$

## Calculate Transformation ratio:

## Transformer on No-load:

$\mathrm{I}_{\mathrm{OC}}=\quad \mathrm{V}_{\mathrm{OC}}=\quad \mathrm{W}_{\mathrm{OC}}=$

Short Circuit Test
$\mathrm{I}_{\mathrm{sc}}=\quad \mathrm{V}_{\mathrm{sc}}=\quad \mathrm{W}_{\mathrm{Sc}}=$

## Calculation

Core loss $=\mathrm{W}_{\mathrm{OC}}=$
$\Phi_{0}=$
$\mathrm{I}_{\mathrm{W}}=\mathrm{I}_{\mathrm{OC}} \cos \Phi_{0}=$
$\mathrm{I} \mu=\mathrm{I}_{\mathrm{OC}} \sin \Phi_{0}=$
Core resistance (ref. to H.T. side) $=\frac{\mathrm{V}_{\mathrm{OC}}}{\mathrm{I}_{\mathrm{W}}}=$
Core reactance (ref. to H.T. side) $=\frac{V_{O C}}{I_{\mu}}=$
Copper loss $=\mathrm{W}_{\mathrm{Cu}}=\mathrm{W}_{\mathrm{SC}}=$
Equivalent Resistance (ref. to H.T. side) $=\mathrm{R}_{01}=\frac{\mathrm{W}_{S C}}{\mathrm{I}_{S C}{ }^{2}}=$
Equivalent Reactance (ref. to H.T. side) $=X_{01}=\sqrt{\left(V_{S C} / I_{S C}\right)^{2}-R_{01}}{ }^{2}$

Signature of the Lab teacher:

## Experiment no: <br> Experiment name: To determine the regulation of a transformer under different power factor for both Single and Three phase Transformer.

## Introduction:

Regulation is an indication of voltage changes due to change in load. Any equipment is said to have good regulation if this change of voltage is less. It is defined as


For a transformer, for constant primary voltage as load increases, the voltage at the load decreases, as there is voltage drop due to internal resistance and reactance of the transformer. If we know the resistance and reactance of the transformer, its regulation can be determined under various load conditions.

## Equipments:

1. Universal Power Supply Module
2. 1PH Transformer
3. AC Ammeter Module 0-1A
4. AC Voltmeter Module $0-250 \mathrm{~V}$
5. 1PH Wattmeter Module
6. Resistive Load Module
7. Inductive Load Module
8. Capacitive Load Module
9. Connecting Cables


## Connection Diagram:



## Procedure:

1. Make sure all the switches (I1, I2, I3, I4, I5, I6) on the Power Supply are turned OFF (downwards).
2. Make sure all the variable knobs $(K 3, K 4)$ are at the min, counter clock wise (CCW) position.
3. Make connections according to the above diagram.
4. Verify the connection by your Lab Teacher
5. Turn ON Switch II (upwards).
6. Turn Key K2 Clock Wise Once, the Indicator Lamp L1 becomes Green.
7. Turn Knob K3 at min (CCW)
8. Turn ON switch I3 (upwards).
9. Keep all the Loads at OFF position
10. Apply voltage $\mathbf{1 1 0 V}$ on the LT side.
11. Note the readings on AC Voltmeter, Ammeter and Wattmeter Module
12. Now turn ON all the Loads
13. Note the readings on AC Voltmeter, Ammeter and Wattmeter Module

## With R-L Load:



## Procedure:

1. Follow the procedure mentioned on Resistive Load for the above Diagram With R-C Load:


## Procedure:

1. Follow the procedure mentioned on Resistive Load for the above Diagram


## Important parts of a three-phase transformer

2. Core- Core is made by laminated silicon steel
3. Coll-Coil (winding) is simply made by insulated copper wire
4. Transformer oll (mineral oil) - Transformer oil has two functions one is to provide necessary insulation for the core and coll and other one is to absorb the heat produce by the pewer loss of transtormer.
5. Fin Cooding system for heated transformer oil.
6. Bushing. Busting is used to connect the colls (primary and secondary) to the outer circuif for nig fitting and avoiding the contact with transformer tank.
7. Conservator Conservator holds the excess oll when the oll gets expanded.
8. Breather with Silica gel Breather is used to pass the air inward and outward of a transtormer through conservator and silica gel absort the moisture of air.
B. Transformer tank. Transformer tank houses core, coll and oil.

## Connection to form three-phase transformer:



## Procedure:

14. Select three 1- $\phi$ transformers of identical manufacturer.
15. Make sure all the switches (I1, I2, I3, I4, 15, I6) on the Power Supply are turned OFF (downwards).
16. Make sure all the variable knobs $(\mathrm{K} 3, \mathrm{~K} 4)$ are at the min, counter clock wise (CCW) position.
17. Make connections according to the above diagram.
18. Verify the connection by your Lab Teacher
19. Now verify the advantages for each type of combination.
20. Keep all the Loads at OFF position
21. Apply voltage $\mathbf{1 1 0 V}$ on the LT side.
22. Note the readings on AC Voltmeter, Ammeter and Wattmeter Module.
23. Now turn ON all the Loads.
24. Note the readings on AC Voltmeter, Ammeter and Wattmeter Module. With constant resistive load determine the efficiency for each combination.

## Report:

Draw the vector diagrams under unity, lagging and leading pf and calculate analytically the experimental value.

Comment on the regulation under leading pf is it something different? Comment on this value.

## Data Sheet

With Resistive Load

| Terminal Voltage $=$ Load current $=$ <br> With $R-L$ Load  | Load power $=$ |  |
| :--- | :--- | :--- |
| Terminal Voltage $=$ <br> With $R-C$ Load | Load current $=$ | Load power $=$ |
| Terminal Voltage $=$ | Load current $=$ | Load power $=$ |

## With $\Delta-\Delta$ connection

With Resistive Load
Terminal Voltage $=$ With R-L Load
Terminal Voltage $=$

| Load current $=$ | Load power $=$ |
| :--- | :--- |
| Load current $=$ | Load power $=$ |
| Load current $=$ | Load power $=$ |

Terminal Voltage $=$
Load current $=$
Load power =

## With Y Y connection

With Resistive Load

| Terminal Voltage $=$ | Load current $=$ | Load power $=$ |
| :--- | :--- | :--- |
| With $R-L$ Load | Load current $=$ | Load power $=$ |
| With $R$ Voltage $=$ <br> Terminal Voltage $=$ | Load current $=$ | Load power $=$ |

With $Y$ - $\Delta$ connection
With Resistive Load
Terminal Voltage = With R-L Load
Terminal Voltage $=$

| Load current $=$ | Load power $=$ |
| :--- | :--- |
| Load current $=$ | Load power $=$ |

With $\Delta-Y$ connection
With Resistive Load
Terminal Voltage $=$

| Load current $=$ | Load power $=$ |
| :--- | :--- |
| Load current $=$ | Load power $=$ |
| Load current $=$ | Load power $=$ |

## Signature of the lab Teacher

Experiment no: 3
Experiment name: Open Circuit Characteristics (OCC) Of Separately- Excited Shunt Generator

## Introduction:

In this type of generator, the field coil is energized from an independent external DC source. The circuit diagram of a separately excited shunt generator is shown below:


Fig: Separately Excited Shunt Generator
Voltage developed in the DC generator in general form, $E_{G}=\phi Z N / 60$ * ( $P / A$ ) volt
Where, $\mathrm{E}_{\mathrm{G}}=$ Generated Emf.
$\phi=$ Flux/pole in Weber.
Z = Total no of armature conductors.
$\mathrm{N}=$ Armature rotation in rpm.
$P=$ No of generator poles.
$A=$ No of parallel paths in armature.
For a given D.C machine $Z, P, A$ are constant. So the voltage equation becomes $\mathbf{E}_{\mathbf{G}}=\mathbf{K}_{\mathbf{g}} \boldsymbol{\phi} \mathbf{N}$ volt, Where $\mathrm{K}_{\mathrm{g}}=\mathrm{ZP} /(60 * \mathrm{~A})$

If armature rotation is constant, then $\mathbf{E}_{\mathbf{G}}=\mathbf{K} \phi$ volt.

So the generated voltage is directly proportional to field flux, i.e. field current $I_{f}$. One of the generator characteristics is defined by the O.C.C i.e. open circuit characteristics.

The shape of the O.C.C is same for all kinds of generator whether separately excited or self excited. It shows the relation between the no-load generated voltage in armature, $\mathrm{E}_{\mathrm{G}}$ and the field or exciting current $I_{f}$ at a given speed.

It is just the magnetization curve for the material of the electromagnet.

## Circuit Diagram:



## Equipments:

```
Universal Power Supply
3PH Squirrel Cage Induction Motor (Prime Mover)
DC Motor / Generator
Field Rheostat
DC Voltmeter / Ammeter Module
Coupling Sleeve
Connecting Cables
```


## Procedure:

1. Make sure all the switches (I1, I2, I3, I4, I5, I6) on the Power Supply are turned OFF (downwards).
2. Make sure all the variable knobs $(K 1, K 3, K 4)$ are at the min, counter dock wise (CCW) position.
3. With a sensitive Multi-meter, measure the shunt field and armature resistance; write the values on the data sheet.
4. Make connections according to the above diagram.
5. Verify the connection by your Lab Teacher
6. Make sure the 3PH Squirrel Cage Induction Motor is mechanically coupled with DC Motor / Generator through the coupling sleeve.
7. Turn ON Switch I1 (upwards).
8. Turn Key K2 Clock Wise Once, the Indicator Lamp L1 becomes Green.
9. Make the 3 PH supply at 400 V by turning Knob K1, the Voltmeter V1 reading 400 V .
10. Turn ON Switch 12 (upwards).
11. 3PH Squirrel Cage Induction Motor should start running at this point.
12. Also DC Motor / Generator starts running since it is mechanically coupled with 3PH Squirrel Cage Induction Motor.
13. Take reading Voc on DC Voltmeter Module (0-250V), If $=0$.
14. Turn Knob K4 at min (CCW)
15. Turn ON switch I4 (upwards).
16. Increase Shunt Field DC Voltage to 220V, Turn Knob K4 CW, Voltmeter V3 reading 220 V
17. Vary Field Rheostat from Min to Max and take readings of Voc \& If. Fill up the table-1. Plot Voc vs. If.

## Report:

1. Why does the curve tend to become horizontal after a certain value of field current?
2. Can you use the same machine as self-excited generator? Explain.
3. What will happen to the O.C.C curve, if the speed of the prime mover is increased?
4. What is the reason of having some voltage without any excitation?

## Group No: <br> Roll no:

## Data Sheet

Armature resistance, $\mathbf{R}_{\mathrm{a}}=$
Field resistance, $\mathbf{R}_{\text {sh }}=$

## Table-1

| Field current <br> $\mathbf{I}_{\mathbf{f}}(\mathbf{m A})$ | Open circuit voltage <br> $\mathbf{V}_{\mathbf{o c}}$ (volt) |
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Calculation and Graph
Plot $\mathbf{V}_{\text {oc }}$ Vs. $\mathbf{I}_{\mathbf{f}}$ on a graph paper and determine the value of critical resistance from this plot.

## Signature of the Lab teacher:

## Sample Data \& Graph

| Field current <br> $\mathbf{I}_{\mathbf{f}}(\mathbf{m A} \mathbf{)}$ | Open circuit voltage <br> $\mathbf{V}_{\mathbf{o s}}($ volt $)$ |
| :---: | :---: |
| 0 | 22 |
| 95 | 161 |
| 110 | 176 |
| 120 | 185 |
| 130 | 194 |
| 145 | 204 |
| 160 | 212 |
| 180 | 222 |
| 190 | 224 |
| 200 | 224 |
| 210 | 224 |

## Plot of O.C.C:



Experiment no: 4
Experiment name: Determination of losses of a DC machine.

## Introduction:

When a DC machine runs either as a motor or generator, losses take place.
These losses are:
Copper losses: Armature copper loss + field copper loss.
Magnetic losses: Eddy current loss + Hysteresis loss
Mechanical losses: Friction loss + bearing loss
Magnetic losses and mechanical losses are collectively known as stray losses. They are also known as rotational losses.

## Equipments:

1. Universal Power Supply
2. DC Motor / Generator
3. Field Rheostat
4. DC Voltmeter / Ammeter Module
5. Tachometer
6. Multimeter
7. Coupling Sleeve
8. Connecting Cables


Figure 8 - Motor Construction

## Connection Diagram:



## Procedure:

1. Make sure all the switches ( $11,12,13,14,15,16$ ) on the Power Supply are turned OFF (downwards)
2. Make sure all the variable knobs (K3, K4) are at the min, counter clock wise (CCW) position.
3. With a sensitive Multi-meter, measure the shunt field and armature resistance; write the values on the data sheet.
4. Make connections according to the above diagram.
5. Verify the connection by your Lab Teacher
6. Turn ON Switch I1 (upwards).
7. Turn Key k2 Clock Wise Once, the Indicator Lamp L1 becomes Green.
8. Make sure the 3 PH supply Voltmeter V 1 reading 400 V .
9. Turn Knob K 4 at $\min$ (CCW)
10. Turn ON switch 14 (upwards).
11. SLOWLY Increase Armature DC Voltage to 120V, Turn Knob K4 CW, Voltmeter V3 Adjust field rheostat to obtain the rated speed 3000RPM
12. Now increase the armature voltage by 20 V in each step and adjust the speed to rated speed 3000 RPM by varying field rheostat.
13. Take readings up to rated armature voltage 220 V . Fill-up the table-1.
14. Now repeat step 11-13, adjust field rheostat to obtain $75 \%$ of rated speed 3000 RPM fill-up table-2.

## Calculation + Graph:

1. Calculate copper losses, total power input and armature power output, Po
2. Po vs. armature voltage, Va using the data of table-1 and draw a tangent and extend the tangent to $Y$-axis. This interception at the $Y$-axis is the mechanical loss of a machine at rated speed.
3. Repeat step-2 using the data of table-2.
4. At first from plot-1 find Po for a voltage say 180 V . Then subtract mechanical loss (from step-2) from that Po. This will represent the Eddy current and Hysteresis loss. Term this loss as $W_{1}$.
5. Repeat step-4 using plot-2 and term this loss as $\mathbf{W}_{2}$.
6. Now use this equation to isolate Eddy current and Hysteresis loss.
7. $W_{1}=A N_{1}+B N_{1}{ }^{2}$, where $N_{1}$ is rated speed
8. $W_{2}=A N_{2}+B N^{2}{ }^{2}$, where $N_{2}$ is $75 \%$ of rated speed.
9. $A$ and $B$ are Eddy current and Hysteresis loss respectively. Solve two equations to find $A$ and $B$.

## Report:

1. Discuss about the nature of Po vs. armature voltage curve at two different speeds.
2. Comment on the results.

## Data Sheet

Group No:
Armature resistance, $\mathrm{R}_{\mathrm{o}}=$
Field resistance, $\mathrm{R}_{\mathrm{sh}}=$
Rated Speed, $N=$
Rated Voltage $=$
At rated Speed, $N=$

| (A) | (B) | (C) | (D) | (E) | (F) | (G) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $V_{0}$ (Volt) | $\begin{aligned} & \mathrm{I}_{\mathrm{a}} \\ & \text { (D)-(C) } \\ & \text { (Amp) } \end{aligned}$ | $I_{t}$ <br> (Amp) | Total Current, I (Amp) | Copper loss <br> (Watt) $V_{a} I_{f}+I_{a}{ }^{2} R_{a}$ | $\begin{aligned} & \text { Power Input } \\ & \text { (watt) } \\ & \text { Va } \times I \\ & (A) \times(D) \\ & \hline \end{aligned}$ | Armature Power Output (watt) $\mathrm{PO}=(\mathrm{F})-(\mathrm{E})$ |
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Table-1
At 75\% of rated Speed, $N=$

| (A) | (B) | (C) | (D) | (E) | (F) | (G) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Va <br> (Volt) | $I_{a}$ <br> (Amp) | (Amp) | Total Current, I $(B)+(C)$ | $\begin{aligned} & \text { Copper loss } \\ & \text { (Watt) } \\ & V_{a} I_{t}+I_{a}{ }^{2} R_{a} \end{aligned}$ | Power Input (watt) <br> (A) $\times(\mathrm{D})$ | Armature Power Output (watt) $\mathrm{P}_{\mathrm{O}}=(\mathrm{F})-(\mathrm{E})$ |
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Signature of the Lab Teacher

## Experiment no:

 5
## Experiment name:

## Introduction:

Voltage developed in the D.C generator in general form ---

$$
\begin{equation*}
E_{g}=\phi Z N / 60 *(P / A) \text { volt } \tag{1}
\end{equation*}
$$

The same equation can be written for motor replacing $\mathbf{E}_{\mathrm{g}}$ by $\mathbf{E}_{\mathrm{b}}$--$E_{b}=\phi Z N / 60 *(P / A)$ volt

Where, $\mathbf{E}_{\mathbf{b}}$ is called the Back EMF.
The simple diagram of a DC motor is shown below:


Figure 1: DC Motor
From the diagram, $E_{b}=V-I_{a} * R_{d}$ Where, $V=$ Supply voltage in volt.
$\mathrm{I}_{\mathrm{a}}=$ Armature Current in Ampere.
$\mathrm{R}_{\mathrm{a}}=$ Armature Resistance in Ohm.

From the equation (1) we get $---E_{b}=\phi^{*} N\left(Z^{*} P / 60 * A\right)$ $=\phi^{*} N^{*} K$, where $K$ is constant

$$
\text { i.e. } \begin{aligned}
N & =(1 / K) * E_{b} / \phi \\
& =K_{m} *\left(V-I_{a} * R_{a}\right) / \phi \text { r.p.m }
\end{aligned}
$$

So the speed of the DC motor is directly proportional to the supplied voltage applied across the armature and Proportionally decreasing with armature current. The speed is also inversely proportional to the field flux i.e. field current.

So the speed of the DC motor can be controlled by three methods. They are-

1. Flux Control
2. Armature Resistance Control
3. Voltage Control

## Equipments:

1. Universal Power Supply
2. DC Motor / Generator
3. Field Rheostat
4. DC Voltmeter / Ammeter Module
5. Coupling Sleeve
6. Connecting Cables
7. Multimeter

Flux Control Method:


## Procedure:

1. Make sure all the switches (I1, I2, 13, I4, I5, I6) on the Power Supply are turned OFF (downwards).
2. Make sure all the variable knobs (K3, K4) are at the min, counter clock wise (CCW) position.
3. With a sensitive Multi-meter, measure the Series, Shunt field and Armature resistance; write the values on the data sheet.
4. Make connections according to the above diagram.
5. Verify the connection by your Lab Teacher
6. Turn ON Switch I1 (upwards).
7. Turn Key K2 Clock Wise Once, the Indicator Lamp L1 becomes Green.
8. Turn Knob K4 at min (CCW)
9. Turn ON switch I4 (upwards).
10. Keep the Field Rheostat to the Min
11. Make the Motor running by increasing the voltage to 200VDC
12. Make the supply voltage at 200VDC and keep Field Rheostat at minimum position.
13. Now vary the Field Rheostat and measure the field current $\mathbf{I}_{\mathbf{q}}$ and the motor speed $\mathbf{N}$ and fill up the Table-1.
b) Armature Resistance Control:


## Procedure:

1. Follow the steps from 1-11 of Flux Control Method
2. Make the Motor running by increasing the voltage to 200VDC
3. Make the supply voltage at 200VDC and keep Field Rheostat at minimum position.
4. Now vary the Field Rheostat and measure the Armature current la and the motor speed $N$ and fill up the Table-2.

## c) Voltage Control:



## Procedure:

1. Follow the steps from 1-11 of Flux Control Method
2. Make the Motor running by increasing the voltage to 200VDC
3. Make the supply voltage at $\mathbf{1 2 0 V D C}$
4. Increase the supply voltage and fill up the Table-3.

## Report:

1. Explain the curves plotted on the graph paper.
2. Variation of which parameter affects the speed most? Why?
3. Explain the relative merits and demerits of each method.
4. What the significance of Back EMF? Briefly explain.


| Table-1 |  | Table-2 |  | Table-3 |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{I}_{1}(\mathrm{~mA})$ | N(rpm) | $\mathrm{I}_{\mathrm{a}}(\mathrm{mA})$ | N(rpm) | $\mathbf{V a}$ (volt) | N(rpm) |
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## Graph

Plot $\mathbf{I}_{\mathbf{f}}$ vs. $\mathbf{N}, \mathbf{I}_{\mathbf{a}} \mathbf{v s} . \mathbf{N}$ and $\mathbf{V}_{\mathbf{a}} \mathbf{v s}$. $\mathbf{N}$ on the same graph paper.

## Signature of the Lab Teacher

Experiment no: 6
Experiment name: Determination of Circuit Parameters of a 3 Phase Induction Motor.

## Introduction:

For an induction motor the equivalent circuit referred to secondary (rotor) is basically an $R-X$ circuit with variable s (slip). As load varies, $s$ varies so the magnitude of $R$ varies.


The following tests are required to determine the circuit constants.

1. No-load test
2. Blocked rotor test


## Equipments:

1. Universal Power Supply Module
2. 3 Phase Squirrel Cage Induction Motor
3. AC Ammeter Module 0-1A
4. AC Voltmeter Module $0-250 \mathrm{~V}$
5. 1PH Wattmeter Module
6. Connecting Cables


## A. No-Load Test:



## Procedure:

1. Make sure all the switches (I1, I2, I3, I4, I5, I6) on the Power Supply are turned OFF (downwards).
2. Make sure all the variable knobs ( $\mathrm{K} 1, \mathrm{~K} 3, \mathrm{~K} 4$ ) are at the min, counter clock wise (CCW) position.
3. Make connections according to the above diagram.
4. Verify the connection by your Lab Teacher
5. Turn ON Switch I1 (upwards).
6. Turn Key K2 Clock Wise Once, the Indicator Lamp L1 becomes Green.
7. Turn knob K1, Apply 400VAC on the Stator of the Motor.
8. Turn ON Switch I2 (upwards).
9. 3 Phase Squirrel Cage Motor Starts Running
10. Note the readings on AC Voltmeter, Ammeter and Wattmeter Module

## B. Blocked Rotor Test

This is also known as locked rotor or short circuit test. This test is used to find:
(i) Short circuit current with normal voltage applied to the stator.
(ii) Power factor on short circuit
(iii) To plot the circle diagram.
(iv) To find resistance of motor R01 and leakage reactance X01 (ref. to primary).


## Procedure:

1. Make sure all the switches (I1, I2, I3, I4, I5, I6) on the Power Supply are turned OFF (downwards).
2. Make sure all the variable knobs (K1, K3, K4) are at the min, counter clock wise (CCW) position.
3. Make connections according to the above diagram.
4. Verify the connection by your Lab Teacher
5. Turn ON Switch I1 (upwards).
6. Turn Key K2 Clock Wise Once, the Indicator Lamp L1 becomes Green.
7. **IMPORTANT: Make the Stator Voltage OVAC
8. **IMPORTANT: Note the Rated Stator Current of the 3 Phase Squirrel Cage Motor
9. **IMPORTANT: Turn ON Switch I2 (upwards).
10. **IMPORTANT: Block the rotor and slowly increase the voltage till rated current flows in the stator.
11. Note the readings on AC Voltmeter, Ammeter and Wattmeter Module

## Report:

1. What is slip of an induction motor?
2. Draw the approximate equivalent circuit of an induction motor.
3. Explain, "The principle of an induction motor is similar to that of a transformer."

## Group No: Roll no:

## Data Sheet

## No load test:

$$
\begin{array}{lcc}
\mathrm{W}_{0}= & \mathrm{I}_{0}= \\
\mathrm{R}_{0}=\frac{\mathrm{V}_{0}^{2}}{\mathrm{~W}_{0}} & \mathrm{Z}_{0}=\frac{\mathrm{V}_{0}}{\mathrm{I}_{0}} & \therefore \mathrm{X}_{0}=\sqrt{\mathrm{Z}_{0}^{2}-\mathrm{R}_{0}^{2}} \\
\mathrm{~W}_{0}=\mathrm{V}_{0} \mathrm{I}_{0} \cos \Phi_{0} & \Rightarrow \cos \Phi_{0}=\frac{\mathrm{W}_{0}}{\mathrm{~V}_{0} \mathrm{I}_{0}} &
\end{array}
$$

## Blocked rotor test:

$\mathrm{W}_{\mathrm{SC}}=\quad \mathrm{I}_{\mathrm{SC}}=\quad \mathrm{V}_{\mathrm{Sc}}=$
$W_{S C}=V_{S C} I_{S C} \cos \Phi_{S}$, i.e. $\Phi_{\mathrm{S}}=$
$\mathrm{W}_{\mathrm{SC}}=\mathrm{I}_{\mathrm{SC}}{ }^{2} \mathrm{R}_{01} \quad Z_{01}=\frac{\mathrm{V}_{\mathrm{SC}}}{\mathrm{I}_{\mathrm{SC}}}$
$\therefore \mathrm{X}_{01}=\sqrt{\mathrm{Z}_{01}{ }^{2}-\mathrm{R}_{01}{ }^{2}}$

Signature of the lab Teacher

## Introduction:

Three quantities are required to describe the behavior of a synchronous generator. These are:

1. The relationship between field current and flux, i.e. EA Vs If.
2. Synchronous reactance.

## 3. Armature resistance.

The first step is to perform the open circuit test. To perform this test, the generator is turned at the rated speed. The terminals are disconnected from load and the field current is set to zero. Then the field current is a gradually increased in step and the corresponding terminals voltage is measured. Plotting of VT Vs If gives the open circuit characteristic of the generator (O.C.C).

## Equipments:

1. 3- $\varphi$ synchronous generator
2. 3- $\varphi$ induction motor
3. $D C$ ammeter $(0-500 \mathrm{~mA})$
4. AC ammeter (0-2.5 A)
5. AC voltmeter (0-300 V)
6. Rheostat ( $0-1000 \Omega$ )
7. Tachometer
8. Wire for connection.


## Connection Diagram:



Fig 01: Open Circuit Test


Fig 02: Short Circuit Test


## Procedure:

1. Make sure all the switches (I1, 12, 13, 14, 15, 16) on the Power Supply are turned OFF (downwards).
2. Make sure all the variable $k n o b s(K 1, K 3, K 4)$ are at the min, counter clock wise (CCW) position.
3. Make connections according to the above diagram.
4. Verify the connection by your Lab Teacher
5. Make sure the 3 PH synchronous Motor / Generator is mechanically coupled with DC Motor / Generator through the coupling sleeve.
6. Turn ON Switch I1 (upwards).
7. Turn Key K2 Clock Wise Once, the Indicator Lamp L1 becomes Green.
8. Make the 3 PH supply at 400VAC by turning Knob K1, Voltmeter V1
9. **Starting the Prime Mover
10. Keep the Field Rheostat of the DC Motor at Maximum
11. Turn ON Switch I6 (upwards).

Obtain speed 3000 RPM by varying the Field Rheostat, measure the speed with Tachometer

## For Open circuit test:

12. Put highest resistance in the rotor of the alternator.
13. Open the stator terminals. Apply voltage on the rotor while the prime mover is rotating at the rated speed.
14. Slowly increase the field current and fill up the table for O.C test.

## For Short circuit test:

15. Put highest resistance in the rotor of the alternator.
16. Short the stator terminals. Apply voltage on the rotor while the prime mover is rotating at the rated speed.
17. Slowly increase the field current and fill up the table for S.C. test.
18. For each step, at constant If, divide $V_{T}$ by $I_{S C}$ to determine $X_{S}$.

## Report:

1. On the same graph paper draw $\mathrm{V}_{\mathrm{T}} \mathrm{Vs} \mathrm{I}_{\mathrm{f}} \mathrm{I}_{\mathrm{Sc}} \mathrm{VS}_{\mathrm{f}} \mathrm{I}_{\mathrm{f}}$ and $\mathrm{X}_{\mathrm{S}} \mathrm{Vs} \mathrm{I}_{\mathrm{f}}$.
2. Why the value of $X_{s}$ does not remain constant?
3. Why do you get a linear relationship between $I_{A} V s I_{f}$ during short circuit test?

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## Data Sheet



## By Calculation



## Signature of the Lab teacher:

